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**Jones**

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(54) **ROBOT OBSTACLE DETECTION SYSTEM**

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(51) **Int. Cl.**  
**G06F 19/00** (2006.01)

(52) **U.S. Cl.** ..... **700/245**; 700/258; 318/568.1; 318/568.12; 318/568.16; 318/568.17; 901/47; 701/23; 701/25

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See application file for complete search history.

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(57) **ABSTRACT**

A robot obstacle detection system including a robot housing which navigates with respect to a surface and a sensor subsystem having a defined relationship with respect to the housing and aimed at the surface for detecting the surface. The sensor subsystem includes an optical emitter which emits a directed beam having a defined field of emission and a photon detector having a defined field of view which intersects the field of emission of the emitter at a region. A circuit in communication with a detector redirects the robot when the surface does not occupy the region to avoid obstacles. A similar system is employed to detect walls.

**34 Claims, 20 Drawing Sheets**

